

# sirius SOFT STARTERS



3RW44  
for High-Feature  
Applications



**SIEMENS**



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# Low-Voltage Controls and Distribution **SIRIUS · SENTRON · SIVACON**

## Catalog LV 1 News 3RW44 Soft Starters · 06/2006

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Catalog LV 1 News · April 2006,  
Chapter 6, Load Feeders, Motor  
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Section 3RW44 Soft Starters  
for High-Feature Applications

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# Explanations

## Delivery times (DT)

- ▶ Preferred type Preferred types are available immediately from stock, i.e. are dispatched within 24 hours.
- A 2 working days
- B 1 week
- C 3 weeks
- D 6 week
- X on request In exceptional cases, the actual delivery period may differ from that specified.

The delivery periods apply up to the ramp at Siemens AG (products ready for dispatch). The transport times depend on the destination and type of shipping. The standard transport time for Germany is 1 day. The delivery times specified here represent the state of 06/2006. They are permanently optimized. Up-to-date information can be found at [www.siemens.com/automation/mall](http://www.siemens.com/automation/mall).

## Price units (PU)

The price unit defines the number of units, sets or meters to which the specified price and weight apply.

## Packaging sizes (PS)

The packaging size defines the number, e.g. of units, sets or meters, for outer packaging.  
Only the quantity defined by the packaging size or a multiple thereof can be ordered!

For multi-unit packaging and recyclable packaging, see Appendix of the LV 1 catalog 2006.

## Price groups (PG)

Each product is assigned to a price group.

## Weight

The defined weight in kg refers to the price unit (PU).

## Dimensions

All dimensions in mm.

# 6

## Load Feeders, Motor Starters and Soft Starters



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# 3RW Soft Starters

## General data

### Overview

The advantages of the SIRIUS soft starters at a glance:

- Soft starting and smooth ramp-down<sup>1)</sup>
- Stepless starting
- Reduction of current peaks
- Avoidance of mains voltage fluctuations during starting
- Reduced load on the power supply network

- Reduction of the mechanical load in the operating mechanism
- Considerable space savings and reduced wiring compared with conventional starters
- Maintenance-free switching
- Very easy handling
- Fits perfectly in the SIRIUS modular system



	SIRIUS 3RW30/31 Standard applications	SIRIUS 3RW40	SIRIUS 3RW44 High-Feature applications
<b>Rated current up to 40 °C</b>	A 3 ... 100	134 ... 432	29 ... 1214
<b>Rated operational voltage</b>	V 200 ... 575	200 ... 600	200 ... 690
<b>Motor rating at 400 V</b>	kW 1.1 ... 55 kW --	75 ... 250 --	15 ... 710 22 ... 1200
<b>Temperature range</b>	°C -25 ... +60	-25 ... +60	0 ... +60
<b>Soft starting/ramp-down</b>	✓ <sup>1)</sup>	✓	✓
<b>Voltage ramp</b>	✓	✓	✓
<b>Starting/stopping voltage</b>	% 40 ... 100	40 ... 100	20 ... 100
<b>Starting and ramp-down time</b>	s 0 ... 20	0 ... 20	1 ... 360
<b>Torque control</b>	--	--	✓
<b>Starting/stopping torque</b>	% --	--	20 ... 100
<b>Torque limit</b>	% --	--	20 ... 200
<b>Ramp time</b>	s --	--	1 ... 360
<b>Integral bypass contact system</b>	✓ <sup>2)</sup>	✓	✓
<b>Intrinsic device protection</b>	--	✓	✓
<b>Motor overload protection</b>	--	✓	✓
<b>Thermistor motor protection</b>	--	--	✓
<b>Adjustable current limiting</b>	--	✓	✓
<b>Inside-delta circuit</b>	--	--	✓
<b>Breakaway pulse</b>	--	--	✓
<b>Creep speed in both directions</b>	--	--	✓
<b>Pump ramp-down</b>	--	--	✓ <sup>6)</sup>
<b>DC braking</b>	--	--	✓ <sup>3) 6)</sup>
<b>Combined braking</b>	--	--	✓ <sup>3) 6)</sup>
<b>Motor heating</b>	--	--	✓
<b>Communication</b>	--	--	with PROFIBUS DP (optional) (optional)
<b>External display and operator module</b>	--	--	
<b>Operating measured value display</b>	--	--	✓
<b>Error logbook</b>	--	--	✓
<b>Event list</b>	--	--	✓
<b>Slave pointer function</b>	--	--	✓
<b>Trace function</b>	--	--	✓ <sup>4)</sup>
<b>Programmable control inputs and outputs</b>	--	--	✓
<b>Number of parameter sets</b>	1 (2 with 3RW31)	1	3
<b>Parameterization software (Soft Starter ES)</b>	--	--	✓
<b>Power semiconductors (thyristors)</b>	2 controlled phases	2 controlled phases	3 controlled phases
<b>Spring-loaded terminals</b>	✓ (only 3RW30 03)	✓	✓
<b>Screw terminals</b>	✓	✓	✓
<b>UL/CSA</b>	✓ <sup>5)</sup>	✓	✓
<b>CE marking</b>	✓	✓	✓
<b>Soft starting under heavy starting conditions</b>	--	--	✓ <sup>6)</sup>
<b>Configuring support</b>	Win-Soft Starter, the electronic selection slider ruler, Technical Assistance +49 911 895 5900		

- ✓ Function is available  
-- Function not available.

- 1) Only soft starting available for 3RW30 ..-1AA12 and 3RW31.  
2) Not available for 3RW30 03.

- 3) Not possible in inside-delta circuit.  
4) Trace function with Soft Starter ES.  
5) For 3RW30 03 up to 230 V.

- 6) Calculate soft starter and motor with size allowance where required.  
More information can be found on the Internet at

<http://www.siemens.com/softstarter>

### Overview

In addition to soft starting and soft ramp-down, the solid-state SIRIUS 3RW44 soft starters provide numerous functions for higher-level requirements. They cover a rating range up to 710 kW (at 400 V) in the inline circuit and up to 1200 kW (at 400 V) in the inside-delta circuit.

The SIRIUS 3RW44 soft starters are characterized by a compact design for space-saving and clearly arranged control cabinet layouts. For optimized motor starting and stopping the innovative SIRIUS 3RW44 soft starters are an attractive alternative with considerable savings potential compared to applications with a frequency converter. The new torque control and adjustable current limiting enable the High-Feature soft starters to be used in nearly every conceivable task. They guarantee the reliable avoidance of sudden torque applications and current peaks during motor starting and stopping. This creates savings potential when calculating the size of the switchgear and when servicing the machinery installed. Be it for inline circuits or inside-delta circuits – the SIRIUS 3RW44 soft starter offers savings especially in terms of size and equipment costs.

Combinations of various starting, operating and ramp-down possibilities ensure an optimum adaptation to the application-specific requirements. Operating and commissioning can be performed by means of the user-friendly keypad and a menu-prompted, multi-line graphic display with background lighting. The optimized motor ramp-up and ramp-down can be effected by means of just a few settings with a previously selected language. Four-key operation and plain-text displays for each menu point guarantee full clarity at every moment of the parameterization and operation.

### Applicable standards

- IEC 60947-4-2
- UL/CSA

### Application

The SIRIUS 3RW44 solid-state soft starters are suitable for the torque-controlled soft starting and smooth ramp-down as well as braking of three-phase asynchronous motors.

#### *Application areas, e. g.*

- Pumps
- Ventilators
- Compressors
- Water transport
- Conveying systems and lifts
- Hydraulics
- Machine tools
- Mills
- Saws
- Breakers
- Mixers
- Centrifuges
- Industrial cooling and refrigerating systems













# 3RW Soft Starters

## 3RW44 for High-Feature applications

### Function

Equipped with modern, ergonomic user prompting the SIRIUS 3RW44 soft starters can be commissioned quickly and easily using a keypad and a menu-prompted, multi-line display with background lighting. Motor starting and deceleration are optimized quickly, easily and safely with just a few settings in a selectable language. Four-key operation and plain-text displays for each menu point guarantee full clarity at every moment of the parameterization and operation. Measurement values and operating values as well as warning messages and fault indications are output continuously on the front panel during operation and when control voltage is applied. An external display and operator module can be connected by means of a connecting cable to the soft starter, thus enabling active indications and the like to be read directly from the control cabinet door.

The SIRIUS 3RW44 soft starters are equipped with optimum functionality. An integral bypass contact system reduces the power loss of the soft starter during operation. This reliably prevents heating of the switchgear environment. The SIRIUS 3RW44 soft starters have internal intrinsic device protection. This prevents thermal overloading of the power section's thyristors, e.g. due to unacceptably high closing operations.

Wiring work for installing an additional motor overload relay is no longer needed as the SIRIUS 3RW44 soft starters perform this function too. In addition they offer adjustable trip classes and a thermistor motor protection function. As an option the thyristors can also be protected by SITOR semi-conductor fuses from short-circuiting. And even inrush current peaks are reliably avoided thanks to adjustable current limiting.

As a further option the SIRIUS 3RW44 soft starters can be upgraded with a PROFIBUS DP module. Thanks to their communication capability and their programmable control inputs and relay outputs the SIRIUS 3RW44 soft starters can be very easily and quickly integrated in higher-level controllers.

In addition a creep speed function is available for positioning and setting jobs. With this function the motor can be controlled in both directions of rotation with reduced torque and an adjustable, low speed.

On the other hand the SIRIUS 3RW44 soft starters offer a new, combined DC braking function for the fast stopping of driving loads.

### Highlights

- Soft starting with breakaway pulse, torque control or voltage ramp and adjustable torque or current limiting as well as any combination of these, depending on load type
- Integrated bypass contact system to minimize dissipated power
- Various setting options for the starting parameters such as starting torque, starting voltage, ramp-up and ramp-down time, and much more in three separate parameter sets
- Start-up detection
- Inside-delta circuit for savings in terms of size and equipment costs
- Various ramp-down modes selectable: free ramp-down, torque-controlled pump stopping, combined DC braking
- Solid-state motor overload and intrinsic device protection
- Thermistor motor protection
- Keypad with a menu-controlled, multi-line, graphic display with background lighting
- Interface for communication with the PC for more accurate setting of the parameters as well as for control and monitoring
- Simple adaptation to the motor feeder
- Simple mounting and commissioning
- Display of operating states and fault signals
- Connection to PROFIBUS with optional PROFIBUS DP module
- External display and operator module
- System voltages from 200 to 690 V, 50 to 60 Hz
- Applicable up to 60 °C (derating from 40 °C)

## 3RW44 for High-Feature applications

### Technical specifications

Type	Terminal	3RW44 ...-BC3.	3RW44 ...-BC4.
<b>Control electronics</b>			
<b>Rated values</b>			
Rated control supply voltage	A1/A2/PE	V	115 AC -15/+10
• Tolerance		%	230 AC -15/+10
Rated control supply current STANDBY		mA	30 20
Rated control supply current ON		mA	300 500 750 450 170 250 400 200
• 3RW44 2. • 3RW44 3. • 3RW44 4. • 3RW44 5.		mA	300 500 750 450 170 250 400 200
Maximum current (pickup bypass)		mA	1000 2500 6000 4500 500 1250 3000 2500
• 3RW44 2. • 3RW44 3. • 3RW44 4. • 3RW44 5.		mA	1000 2500 6000 4500 500 1250 3000 2500
Rated frequency		Hz	50 ... 60
• Tolerance		%	±10 50 ... 60 ±10
Type	Terminal	3RW44 ..	Factory presetting
<b>Control electronics</b>			
<b>Control inputs</b>			
Input 1	IN1		Start motor right parameter set 1
Input 2	IN2		No action
Input 3	IN3		No action
Input 4	IN4		Trip reset
Supply	L+/L-	mA	Approx. 10 per input to DIN 19240 Internal voltage: 24 V DC from internal supply through terminal L+ to IN1 ... IN4. Maximum load at L+ approx. 55 mA
• Rated operational current • Rated operational voltage	L+		External voltage: DC external voltage (to DIN19240) through terminals L- and IN1 ... IN4 (min. 12 V DC, max. 30 V DC)
	L-		
<b>Thermistor motor protection input</b>			
Input	T1/T2		PTC type A or Thermoclick Deactivated
<b>Relay outputs (floating auxiliary contacts)</b>			
Output 1	13/14		ON period
Output 2	23/24		No action
Output 3	33/34		No action
Output 4	95/96/98		Group fault
<b>Switching capacity of the relay outputs</b>			
230 V/AC-15 24 V/DC-13	A	3 at 240 V 1 at 24 V	
Protection against overvoltages Short-circuit protection			Protection by means of Varistor through relay contact 4 A gL/gG operational class; 6 A quick (fuse is not included in scope of supply)
<b>Protective functions</b>			
<b>Motor protection functions</b>			
Trips in the event of Trip class to IEC 60947-4-1 Phase failure sensitivity	Class %	Thermal overloading of the motor 5/10/15/20/30 > 40 yes Manual/Automatic Manual/Automatic 1 ... 30	10  Manual Manual 1
Overload warning Reset and recovery Reset option after tripping Recovery time	min.		
<b>Device protection functions</b>			
Trips in the event of Reset option after tripping Recovery time	min.	Thermal overloading of the thyristors Manual/Automatic 0.5	Manual

# 3RW Soft Starters

## 3RW44 for High-Feature applications

Type	3RW44 ..			Factory presetting
<b>Control times and parameters</b>				
<b>Control times</b>				
Closing delay (with connected control voltage)	ms	< 50		
Closing delay (automatic mode)	ms	< 4000		
Recovery time (closing command in active ramp-down)	ms	< 100		
<b>Mains failure bridging time</b>				
Control supply voltage	ms	100		
<b>Mains failure response time</b>				
Load current circuit	ms	100		
<b>Reclosing lockout after overload trip</b>				
Motor protection trip	min. s	1 ... 30		1
Device protection trip		30		
<b>Setting options for starting</b>				
Voltage ramp for starting voltage	%	20 ... 100		30
Torque control for starting torque	%	20 ... 100		50
Torque control for limit torque	%	20 ... 200		150
Starting time	s	0 ... 360		20
Maximum starting time	s	1 ... 1000		Deactivated
Current limit value	%	125 ... 550		450
Breakaway voltage	%	40 ... 100		80
Breakaway time	s	0 ... 2		Deactivated
Motor heat output	%	0 ... 100		0
<b>Creep mode Left/Right running</b>				
Speed factor as function of rated speed ( $n = n_{\text{rated}}/\text{factor}$ )	%	3 ... 21		7
Creep torque (reference variable depends on the motor used but is always smaller than the rated torque of the motor)	%	20 ... 100		50
<b>Setting options for ramp-down</b>				
Torque control for stopping torque	%	10 ... 100		10
Ramp-down time	s	0 ... 360		10
Dynamic braking torque	%	20 ... 100		50
DC braking torque	%	20 ... 100		50
<b>Operating indications</b>				
		Test voltage Test mains phases Ready to start Start active Motor running Ramp-down active		
<b>Warnings/error signals</b>				
		Mains voltage missing Leading-edge phase error Phase failure • L1 • L2 • L3 Missing load phase • T1 • T2 • T3 Failure • Contact element 1 (thyristor) • Contact element 2 (thyristor) • Contact element 3 (thyristor) Flash memory faulty Supply voltage • Below 75 % • Below 85 % • Over 110 % Current unbalance exceeded Thermal motor model overload Prewarning limit exceeded • Motor heating • Time-related trip reserve Bypass elements defective Mains voltage too high Device not named Wrong naming version Current range exceeded Motor blocking – shutdown Current limit exceeded Power section • Overheated • Overtemperature Emergency active		

Type	3RW44 ..	Factory presetting
<b>Control times and parameters</b>		
Warnings/error signals (contd.)	<ul style="list-style-type: none"> <li>Temperature sensor</li> <li>• Overload</li> <li>• Open-circuit</li> <li>• Short-circuit</li> <li>Ground fault</li> <li>• Detected</li> <li>• Shutdown</li> <li>Connection abort in manual mode</li> <li>Max. number of starts exceeded</li> <li><math>I_e</math> limit value overshoot/undershoot</li> <li>Cooling time</li> <li>• Motor active</li> <li>• Switch block active</li> <li>Heat sink sensor</li> <li>• Open-circuit</li> <li>• Short-circuit</li> <li>Quick-stop function</li> <li>Switch block faulty</li> <li><math>I_e</math>/class setting not permissible</li> </ul>	
<b>Control inputs</b>		
Input 1 Input 2 Input 3 Input 4		Motor right parameter set 1 No action No action Trip reset
Parameterizing options for control inputs 1 ... 4	No action Local manual mode Emergency start Creep speed Quick-stop Trip reset	
	Motor right parameter set 1 Motor left parameter set 1 <sup>1)</sup> Motor right parameter set 2 Motor left parameter set 2 <sup>1)</sup> Motor right parameter set 3 Motor left parameter set 3 <sup>1)</sup>	
<b>Relay outputs</b>		
Output 1 Output 2 Output 3 Output 4		ON period No action No action Group fault
Parameterizing options for relay outputs 1 ... 3	No action PAA output 1 PAA output 2 Input 1 Input 2 Input 3 Input 4 Ramp-up Operation/Bypass Ramp-down ON period Command motor on Fan DC braking contactor Group warning Group fault Bus fault Device error Power on Ready to start	
<b>Motor temperature sensors</b>	Deactivated Thermoclick PTC type A	Deactivated

1) Parameter motor left possible only in conjunction with creep mode.



Type		3RW44 34	3RW44 35	3RW44 36
<b>Power electronics</b>				
<b>Rated operational current <math>I_e</math></b>		113	134	162
<b>Load rating with rated operational current <math>I_e</math></b>				
• Acc. to IEC and UL/CSA for individual mounting, AC-53a				
- at 40 °C	A	113	134	162
- at 50 °C	A	100	117	145
- at 60 °C	A	88	100	125
<b>Smallest adjustable rated motor current <math>I_M</math></b> for the motor overload protection	A	22	26	32
<b>Power loss</b>				
• In operation after completed ramp-up with uninterrupted rated operational current (40 °C) approx.	W	64	76	95
• During starting with current limit set to 350 % $I_M$ (40 °C)	W	1350	1700	2460
<b>Permissible rated motor current and starts per hour</b>				
<b>• Normal starting (Class 5)</b>				
- Rated motor current $I_M^{(1)}$ , starting time 5 s	A	113	134	162
- Starts per hour <sup>(2)</sup>	1/h	41	39	41
- Rated motor current $I_M^{(1)(3)}$ , starting time 10 s	A	113	134	162
- Starts per hour <sup>(2)</sup>	1/h	20	15	20
<b>• Normal starting (Class 10)</b>				
- Rated motor current $I_M^{(1)}$ , starting time 10 s	A	113	134	162
- Starts per hour <sup>(2)</sup>	1/h	20	15	20
- Rated motor current $I_M^{(1)(3)}$ , starting time 20 s	A	113	134	162
- Starts per hour <sup>(2)</sup>	1/h	9	6	7
<b>• Normal starting (Class 15)</b>				
- Rated motor current $I_M^{(1)}$ , starting time 15 s	A	113	134	162
- Starts per hour <sup>(2)</sup>	1/h	13	9	12
- Rated motor current $I_M^{(1)(3)}$ , starting time 30 s	A	113	134	162
- Starts per hour <sup>(2)</sup>	1/h	6	6	1
<b>• For heavy starting (Class 20)</b>				
- Rated motor current $I_M^{(1)}$ , starting time 20 s	A	106	125	147
- Starts per hour <sup>(2)</sup>	1/h	9	9	10
- Rated motor current $I_M^{(1)(3)}$ , starting time 40 s	A	106	125	147
- Starts per hour <sup>(2)</sup>	1/h	1.5	2	1
<b>• For very heavy starting (Class 30)</b>				
- Rated motor current $I_M^{(1)}$ , starting time 30 s	A	91	110	120
- Starts per hour <sup>(2)</sup>	1/h	6	6	6
- Rated motor current $I_M^{(1)(3)}$ , starting time 60 s	A	91	110	120
- Starts per hour <sup>(2)</sup>	1/h	2	2	2

1) Current limit on soft starter set to 350 %  $I_M$ .2) For intermittent duty S4 with ON period = 70 %,  $T_u = 40$  °C, stand-alone installation vertical. The quoted operating frequencies do not apply for automatic mode.3) Maximum adjustable rated motor current  $I_M$ , dependent on CLASS setting.

# 3RW Soft Starters

## 3RW44 for High-Feature applications

Type		3RW44 43	3RW44 44	3RW44 45	3RW44 46	3RW44 47
<b>Power electronics</b>						
<b>Rated operational current <math>I_e</math></b>		203	250	313	356	432
<b>Load rating with rated operational current <math>I_e</math></b>						
• Acc. to IEC and UL/CSA for individual mounting, AC-53a						
- at 40 °C	A	203	250	313	356	432
- at 50 °C	A	180	215	280	315	385
- at 60 °C	A	156	185	250	280	335
<b>Smallest adjustable rated motor current <math>I_M</math></b> for the motor overload protection	A	40	50	62	71	86
<b>Power loss</b>						
• In operation after completed ramp-up with uninterrupted rated operational current (40 °C) approx.	W	89	110	145	174	232
• During starting with current limit set to 350 % $I_M$ (40 °C)	W	3350	4000	4470	5350	5860
<b>Permissible rated motor current and starts per hour</b>						
<b>• Normal starting (Class 5)</b>						
- Rated motor current $I_M^{(1)}$ , starting time 5 s	A	203	250	313	356	432
- Starts per hour <sup>(2)</sup>	1/h	41	41	41	41	39
- Rated motor current $I_M^{(1)(3)}$ , starting time 10 s	A	203	250	313	356	432
- Starts per hour <sup>(2)</sup>	1/h	20	20	19	17	16
<b>• Normal starting (Class 10)</b>						
- Rated motor current $I_M^{(1)}$ , starting time 10 s	A	203	250	313	356	432
- Starts per hour <sup>(2)</sup>	1/h	20	20	19	17	16
- Rated motor current $I_M^{(1)(3)}$ , starting time 20 s	A	203	250	313	356	432
- Starts per hour <sup>(2)</sup>	1/h	9	10	6	4	5
<b>• Normal starting (Class 15)</b>						
- Rated motor current $I_M^{(1)}$ , starting time 15 s	A	203	240	313	325	402
- Starts per hour <sup>(2)</sup>	1/h	13	13	10	13	11
- Rated motor current $I_M^{(1)(3)}$ , starting time 30 s	A	203	240	313	325	402
- Starts per hour <sup>(2)</sup>	1/h	3	6	1	2	1
<b>• For heavy starting (Class 20)</b>						
- Rated motor current $I_M^{(1)}$ , starting time 20 s	A	195	215	275	285	356
- Starts per hour <sup>(2)</sup>	1/h	10	10	10	10	10
- Rated motor current $I_M^{(1)(3)}$ , starting time 40 s	A	195	215	275	285	356
- Starts per hour <sup>(2)</sup>	1/h	1	5	1	3	1
<b>• For very heavy starting (Class 30)</b>						
- Rated motor current $I_M^{(1)}$ , starting time 30 s	A	162	180	220	240	285
- Starts per hour <sup>(2)</sup>	1/h	6	6	6	6	6
- Rated motor current $I_M^{(1)(3)}$ , starting time 60 s	A	162	180	220	240	285
- Starts per hour <sup>(2)</sup>	1/h	3	3	3	2	1

1) Current limit on soft starter set to 350 %  $I_M$ .

2) For intermittent duty S4 with ON period = 70 %,  $T_u = 40$  °C, stand-alone installation vertical. The quoted operating frequencies do not apply for automatic mode.

3) Maximum adjustable rated motor current  $I_M$ , dependent on CLASS setting.

Type		3RW44 53	3RW44 54	3RW44 55	3RW44 56	3RW44 57	3RW44 58
<b>Power electronics</b>							
<b>Rated operational current <math>I_e</math></b>		551	615	693	780	880	970
<b>Load rating with rated operational current <math>I_e</math></b>							
• Acc. to IEC and UL/CSA for individual mounting, AC-53a							
- at 40 °C	A	551	615	693	780	880	970
- at 50 °C	A	494	551	615	693	780	850
- at 60 °C	A	438	489	551	615	693	760
<b>Smallest adjustable rated motor current <math>I_M</math></b>	A	110	123	138	156	176	194
for the motor overload protection							
<b>Power loss</b>							
• In operation after completed ramp-up with uninterrupted rated operational current (40 °C) approx.	W	159	186	220	214	250	270
• During starting with current limit set to 350 % $I_M$ (40 °C)	W	7020	8100	9500	11100	13100	15000
<b>Permissible rated motor current and starts per hour</b>							
<b>Normal starting (Class 5)</b>							
- Rated motor current $I_M^{(1)}$ , starting time 5 s	A	551	615	693	780	880	970
- Starts per hour <sup>2)</sup>	1/h	41	41	37	33	22	17
- Rated motor current $I_M^{(1)(3)}$ , starting time 10 s	A	551	615	693	780	880	970
- Starts per hour <sup>2)</sup>	1/h	20	20	16	13	8	5
<b>Normal starting (Class 10)</b>							
- Rated motor current $I_M^{(1)}$ , starting time 10 s	A	551	615	693	780	880	970
- Starts per hour <sup>2)</sup>	1/h	20	20	16	13	8	5
- Rated motor current $I_M^{(1)(3)}$ , starting time 20 s	A	551	615	693	780	880	970
- Starts per hour <sup>2)</sup>	1/h	10	9	6	4	0.3	0,3
<b>Normal starting (Class 15)</b>							
- Rated motor current $I_M^{(1)}$ , starting time 15 s	A	551	615	666	723	780	821
- Starts per hour <sup>2)</sup>	1/h	13	13	11	9	8	8
- Rated motor current $I_M^{(1)(3)}$ , starting time 30 s	A	551	615	666	723	780	821
- Starts per hour <sup>2)</sup>	1/h	6	4	3	1	0.4	0,5
<b>For heavy starting (Class 20)</b>							
- Rated motor current $I_M^{(1)}$ , starting time 20 s	A	551	591	633	670	710	740
- Starts per hour <sup>2)</sup>	1/h	10	10	7	8	8	9
- Rated motor current $I_M^{(1)(3)}$ , starting time 40 s	A	551	591	633	670	710	740
- Starts per hour <sup>2)</sup>	1/h	4	2	1	1	0.4	1
<b>For very heavy starting (Class 30)</b>							
- Rated motor current $I_M^{(1)}$ , starting time 30 s	A	500	525	551	575	600	630
- Starts per hour <sup>2)</sup>	1/h	6	6	6	6	6	6
- Rated motor current $I_M^{(1)(3)}$ , starting time 60 s	A	500	525	551	575	600	630
- Starts per hour <sup>2)</sup>	1/h	2	1	1	1	1.5	1

1) Current limit on soft starter set to 350 %  $I_M$ .2) For intermittent duty S4 with ON period = 70 %,  $T_u = 40$  °C, stand-alone installation vertical. The quoted operating frequencies do not apply for automatic mode.3) Maximum adjustable rated motor current  $I_M$ , dependent on CLASS setting.

# 3RW Soft Starters

## 3RW44 for High-Feature applications

Type		3RW44 2.	3RW44 3., 3RW44 4.	3RW44 5.
<b>Conductor cross-sections</b>				
<b>Screw terminals</b>	<b>Main conductors:</b>			
<b>with box terminal</b>				
<b>Front clamping point connected</b>	<ul style="list-style-type: none"> <li>• Finely stranded with end sleeve</li> <li>• Finely stranded without end sleeve</li> <li>• Stranded</li> <li>• Ribbon cable conductors (number x width x thickness)</li> <li>• AWG conductors, solid or stranded</li> </ul>  <span style="font-size: small;">NSB00479</span>	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup> mm AWG	3RT19 55-4G (55 kW) 16 ... 70 16 ... 70 16 ... 70 min. 3 x 9 x 0.8, max. 6 x 15.5 x 0.8 6 ... 2/0	3RT19 66-4G 70 ... 240 70 ... 240 95 ... 300 min. 6 x 9 x 0.8 max. 20 x 24 x 0.5 3/0 ... 600 kcmil
<b>Rear clamping point connected</b>	<ul style="list-style-type: none"> <li>• Finely stranded with end sleeve</li> <li>• Finely stranded without end sleeve</li> <li>• Stranded</li> <li>• Ribbon cable conductors (number x width x thickness)</li> <li>• AWG conductors, solid or stranded</li> </ul>  <span style="font-size: small;">NSB00480</span>	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup> mm AWG	16 ... 70 16 ... 70 16 ... 70 min. 3 x 9 x 0.8, max. 6 x 15.5 x 0.8 6 ... 2/0	120 ... 185 120 ... 185 120 ... 240 min. 6 x 9 x 0.8 max. 20 x 24 x 0.5 250 ... 500 kcmil
<b>Both clamping points connected</b>	<ul style="list-style-type: none"> <li>• Finely stranded with end sleeve</li> <li>• Finely stranded without end sleeve</li> <li>• Stranded</li> <li>• Ribbon cable conductors (number x width x thickness)</li> <li>• AWG conductors, solid or stranded</li> <li>• Terminal screws - Pickup torque</li> </ul>  <span style="font-size: small;">NSB00481</span>	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup> mm AWG	max. 1 x 50, 1 x 70 max. 1 x 50, 1 x 70 max. 2 x 70 max. 2 x (6 x 15.5 x 0.8) max. 2 x 1/0 M10 (hexagon socket, A/F4) 10 ... 12 90 ... 110	min. 2 x 50; max. 2 x 185 min. 2 x 50; max. 2 x 185 max. 2 x 70; max. 2 x 240 max. 2 x (20 x 24 x 0.5) min. 2 x 2/0; max. 2 x 500 kcmil M12 (hexagon socket, A/F5) 20 ... 22 180 ... 195
<b>Screw terminals</b>	<b>Main conductors:</b>			
<b>with box terminal</b>				
<b>Front or rear clamping point connected</b>	<ul style="list-style-type: none"> <li>• Finely stranded with end sleeve</li> <li>• Finely stranded without end sleeve</li> <li>• Stranded</li> <li>• Ribbon cable conductors (number x width x thickness)</li> <li>• AWG conductors, solid or stranded</li> </ul>  <span style="font-size: small;">NSB00479</span>  <span style="font-size: small;">NSB00480</span>	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup> mm AWG	3RT19 56-4G 16 ... 120 16 ... 120 16 ... 120 min. 3 x 9 x 0.8 max. 6 x 15.5 x 0.8 6 ... 250 kcmil	
<b>Both clamping points connected</b>	<ul style="list-style-type: none"> <li>• Finely stranded with end sleeve</li> <li>• Finely stranded without end sleeve</li> <li>• Stranded</li> <li>• Ribbon cable conductors (number x width x thickness)</li> <li>• AWG conductors, solid or stranded</li> </ul>  <span style="font-size: small;">NSB00481</span>	mm <sup>2</sup> mm <sup>2</sup> mm <sup>2</sup> mm AWG	max. 1 x 95, 1 x 120 max. 1 x 95, 1 x 120 max. 2 x 120 max. 2 x (10 x 15.5 x 0.8) max. 2 x 3/0	
<b>Screw terminals</b>	<b>Main conductors:</b>			
	<u>Without box terminal/rail connection</u>			
	<ul style="list-style-type: none"> <li>• Finely stranded with cable lug</li> <li>• Stranded with cable lug</li> <li>• AWG conductors, solid or stranded</li> <li>• Connecting bar (max. width)</li> <li>• Terminal screws - Pickup torque</li> </ul>	mm <sup>2</sup> mm <sup>2</sup> AWG mm NM lb.in	16 ... 95 <sup>1)</sup> 25 ... 120 <sup>1)</sup> 4 ... 250 kcmil 17 M8 x 25 (A/F13) 10 ... 14 89 ... 124	50 ... 240 <sup>2)</sup> 70 ... 240 <sup>2)</sup> 2/0 ... 500 kcmil 25 M10 x 30 (A/F17) 14 ... 24 124 ... 210
				50 ... 240 <sup>2)</sup> 70 ... 240 <sup>2)</sup> 1/0 ... 500 kcmil 60 M12 x 40 20 ... 35 177 ... 310

1) When connecting cable lugs to DIN 46235 use 3RT19 56-4EA1 terminal cover for conductor cross-sections from 95 mm<sup>2</sup> to ensure phase spacing.

2) When connecting cable lugs to DIN 46234, the 3RT19 66-4EA1 terminal cover must be used for conductor cross-sections of 240 mm<sup>2</sup> and more as well as DIN 46235 for conductor cross-sections of 185 mm<sup>2</sup> and more to keep the phase clearance.

Soft starters	Type	3RW44 ..			
<b>Conductor cross-sections</b>					
<b>Auxiliary conductors</b> (1 or 2 conductors can be connected):					
<b>Screw terminals</b> <ul style="list-style-type: none"> <li>• Solid mm<sup>2</sup> 2 x 0.5 ... 2.5</li> <li>• Finely stranded with end sleeve mm<sup>2</sup> 2 x 0.5 ... 1.5</li> <li>• AWG cables AWG 2 x 20 ... 14 - Solid or stranded 2 x 20 ... 16 - Finely stranded with end sleeve</li> <li>• Terminal screws NM 0.7 ... 0.9 - Pickup torque lb.in 7 ... 8</li> </ul>					
<b>Spring-loaded terminals</b> <ul style="list-style-type: none"> <li>• Solid mm<sup>2</sup> 2 x 0.25 ... 2.5</li> <li>• Finely stranded with end sleeve mm<sup>2</sup> 2 x 0.25 ... 1.5</li> <li>• AWG conductors, solid or stranded AWG 2 x 24 ... 14</li> </ul>					
		Standard	Parameters		
<b>Electromagnetic compatibility acc. to EN 60947-4-2</b>					
<b>EMC interference immunity</b>					
Electrostatic discharge (ESD)	EN 61000-4-2	±4 kV contact discharge, ±8 kV air discharge			
Electromagnetic RF fields	EN 61000-4-3	Frequency range: 80 ... 1000 MHz with 80 % at 1 kHz Degree of severity 3, 10 V/m			
Conducted RF interference	EN 61000-4-6	Frequency range: 150 kHz ... 80 MHz with 80 % at 1 kHz Interference 10 V			
RF voltages and RF currents on conductors					
Burst	EN 61000-4-4	±2 kV/5 kHz			
Surge	EN 61000-4-5	±1 kV line to line ±2 kV line to ground			
<b>EMC interference emission</b>					
EMC interference field strength	EN 55011	Limit value of Class A at 30 ... 1000 MHz			
Radio interference voltage	EN 55011	Limit value of Class A at 0.15 ... 30 MHz			
<b>Is an RI suppression filter necessary?</b>					
Degree of noise suppression A (industrial applications)		no			

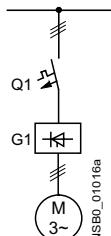
# 3RW Soft Starters

## 3RW44 for High-Feature applications

### Fuse assignment

The coordination type to which the motor feeder with soft starter is mounted depends on the application-specific requirements. Normally, fuseless mounting (combination of motor starter protector and soft starter) is sufficient. If type 2 coordination is to be fulfilled, semiconductor fuses must be fitted in the motor feeder.

#### Inline circuit fuseless version



Soft starters		Motor starter protectors/circuit-breakers <sup>1)</sup>	
G1 Type	Rated current A	440 V +10 % Q1 Type	Rated current A
<b>Type of coordination 1<sup>2)</sup>: 3RW44 22 ... 3RW44 27: <math>I_q = 32 \text{ kA}</math>; 3RW44 34 and 3RW44 35: <math>I_q = 16 \text{ kA}</math>; 3RW44 36 ... 3RW44 57: <math>I_q = 65 \text{ kA}</math></b>			
3RW44 22	29	3RV10 42-4HA10	50
3RW44 23	36	3RV10 42-4JA10	63
3RW44 24	47	3RV10 42-4KA10	75
3RW44 25	57	3RV10 42-4LA10	90
3RW44 26	77	3RV10 42-4MA10	100
3RW44 27	93	3RV10 42-4MA10	100
3RW44 34	113	3VL17 16-2DD36	160
3RW44 35	134	3VL17 16-2DD36	160
3RW44 36	162	3VL37 25-2DC36	250
3RW44 43	203	3VL47 31-3DC36	315
3RW44 44	250	3VL47 31-3DC36	315
3RW44 45	313	3VL47 40-3DC36	400
3RW44 46	356	3VL47 40-3DC36	400
3RW44 47	432	3VL57 50-3DC36	500
3RW44 53	551	3VL67 80-3DE36	800
3RW44 54	615	3VL67 80-3DE36	800
3RW44 55	693	3VL67 80-3DE36	800
3RW44 56	780	3VL77 10-3AB36	1000
3RW44 57	880	3VL77 10-3AB36	1000
3RW44 58	970	3VL77 12-3AB36	1200

1) The rated motor current must be considered when selecting the devices.

2) The types of coordination are explained in more detail in the Technical information LV 1 T under – Fuseless Load Feeders.



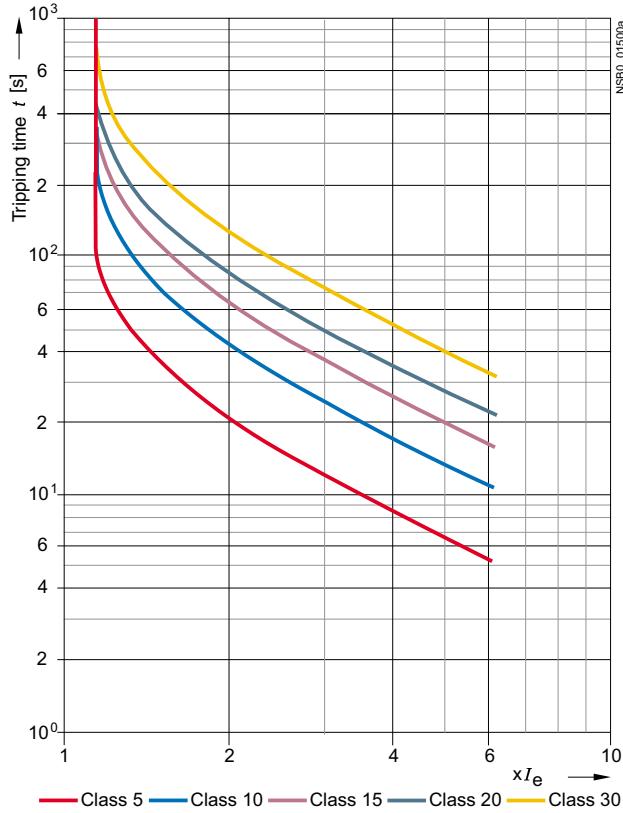




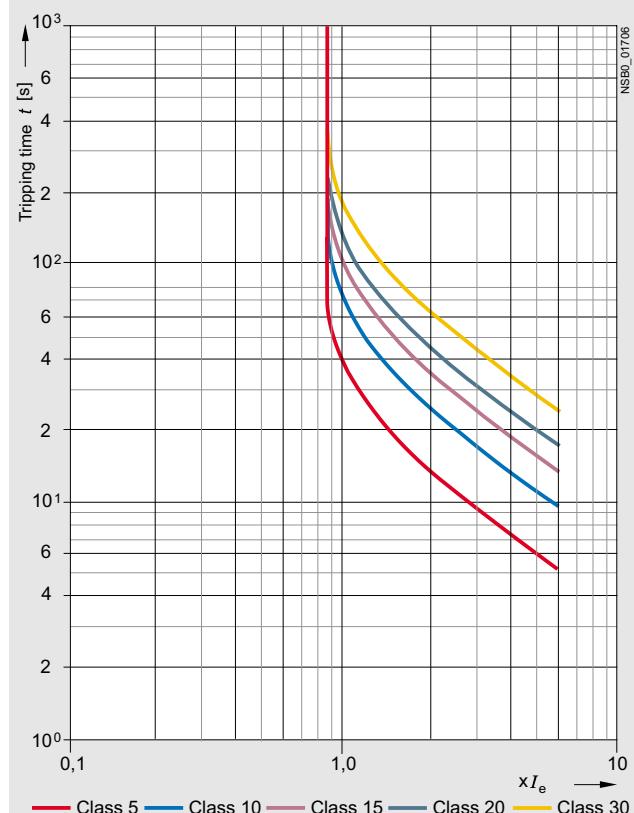


## Characteristic curves

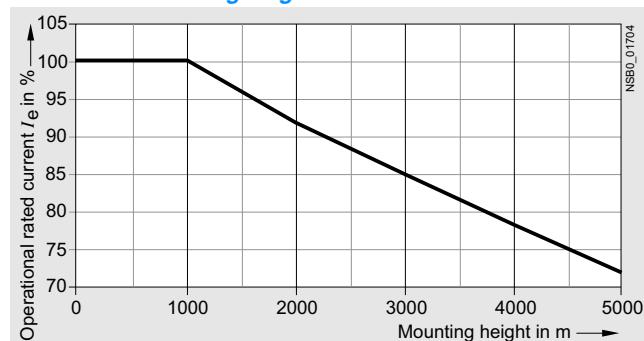
**Motor protection tripping characteristics for 3RW44 (with symmetry)**



**Motor protection characteristics for 3RW44 (with phase unbalance)**



## Admissible mounting height



The admissible operational voltage is reduced to 460 V with a mounting height of more than 2000 m.



## 3RW44 for High-Feature applications

### Circuit concept

The SIRIUS 3RW44 soft starters can be operated in two different types of circuit.

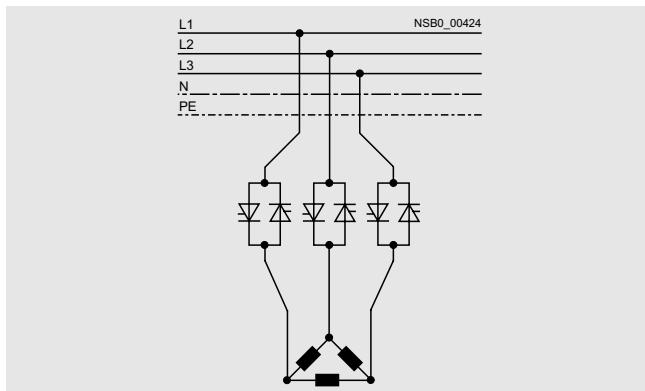
- **Inline circuit**

The controls for isolating and protecting the motor are simply connected in series with the soft starter. The motor is connected to the soft starter with three leads.

- **Inside-delta circuit**

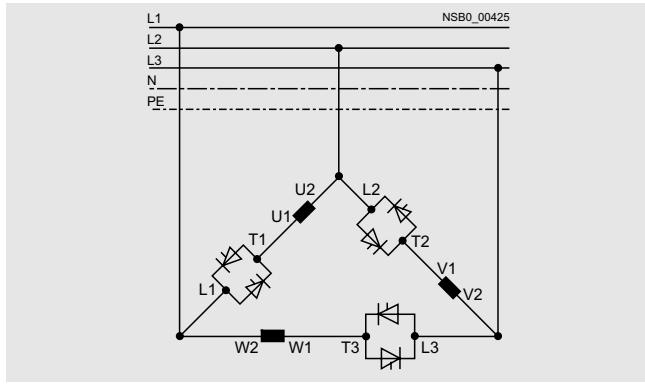
The wiring is similar to that of wye-delta starters. The phases of the soft starter are connected in series with the individual motor windings. The soft starter then only has to carry the phase current, amounting to about 58 % of the rated motor current (conductor current).

### Comparison of the types of circuit



Inline circuit:

Rated current  $I_e$  corresponds to the rated motor current  $I_n$ ,  
3 leads to the motor



Inside-delta circuit:

Rated current  $I_e$  corresponds to approx. 58 % of the rated motor current  $I_n$ ,  
6 leads to the motor (as with wye-delta starters)

### Which circuit?

Using the inline circuit involves the lowest wiring complexity. If the soft starter to motor connections are long, this contact sequence is preferable.

With the inside-delta circuit there is double the wiring complexity but a smaller size of device can be used at the same rating.

Thanks to choosing the operational mode between the inline circuit and inside-delta circuit, the most favorable solution can always be chosen.

The braking function is possible only in the inline circuit.

### Configuration

The 3RW44 solid-state soft starters are designed for normal starting. In case of heavy starting or increased starting frequency, a larger device must be selected.

For long starting times it is recommended to have a PTC thermistor detector in the motor. This also applies for the ramp-down modes smooth ramp-down, pump ramp-down and DC braking, because during the ramp-down time in these modes, an additional current loading applies in contrast to free ramp-down.

In the motor feeder between the SIRIUS 3RW soft starter and the motor, no capacitive elements are permitted (e.g. no reactive-power compensation equipment). In addition, neither static systems for reactive-power compensation nor dynamic PFC (Power Factor Correction) must be operated in parallel during starting and ramp-down of the soft starter. This is important to prevent faults arising on the compensation equipment and/or the soft starter.

All elements of the main circuit (such as fuses and controls) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, switching devices and overload relays must be ordered separately.

The harmonic component load for starting currents must be taken into consideration for the selection of motor starter protectors (selection of release).

#### Note:

*When switching on three-phase current motors voltage drops normally will occur with all types of starters (direct starters, star-delta starters, soft starters). On principle the feeding transformer must be configured such that when starting the motor the voltage drop must occur within the admissible tolerance. When the feeding transformer is designed quite scarce the control voltage (being independent of the main voltage) should be supplied with a separate circuit in order to prevent the soft starter from switching off.*

### Serial PC interface, PROFIBUS DP communication module and parameterizing and operating software Soft Starter ES

The solid-state 3RW44 soft starters have a PC interface for communicating with the Soft Starter ES 2006 Smart software or to be connected to an external operating and monitoring module. When using the optional communication module PROFIBUS the 3RW44 soft starter can be connected to the PROFIBUS net and can communicate via GSD file or software Soft Starter ES 2006 Professional.

### Manual for SIRIUS 3RW44

Besides containing all important information on planning, commissioning and servicing, the manual also contains suggested circuits and the technical specifications for all devices.

### Win-Soft Starter selection and simulation program

With this software, you can simulate and select all Siemens soft starters, taking into account various parameters such as mains properties, motor and load data, and special application requirements.

The software is a valuable tool, which makes complicated, lengthy manual calculations for determining the required soft starters superfluous.

You can order the CD-ROM under the following order number:  
Order No.: E20001-D1020-P302-V2-7400.

More information can be found on the Internet at  
<http://www.siemens.com/softstarter>

# 3RW Soft Starters

## 3RW44 for High-Feature applications

### *SIRIUS soft starter training course (SD-SIRIUSO)*

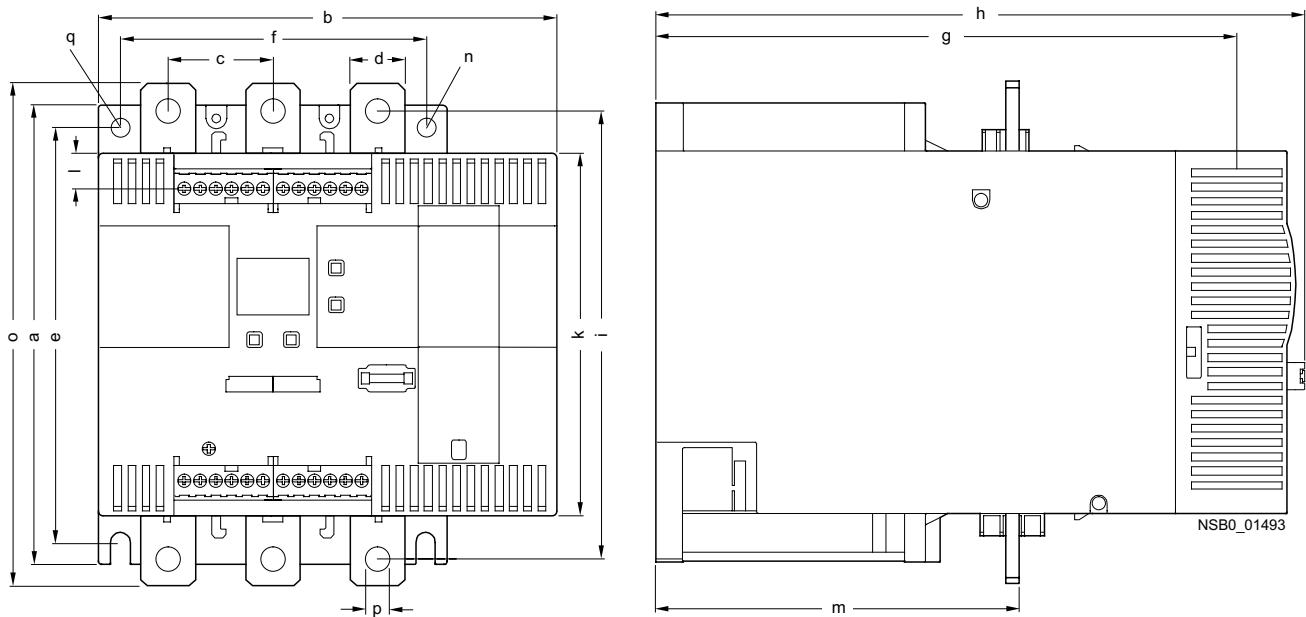
Siemens offers a 2-day training course on the SIRIUS solid-state soft starters to keep customers and own personnel up-to-date on configuring, commissioning and servicing issues.

Please direct enquiries and applications to:

A&D PT 4 (Trainings-Center Erlangen)  
Werner-von-Siemens-Str. 65  
D-91052 Erlangen  
Telefon: ++49 9131 729262  
Telefax: ++49 9131 728172  
[sibrain.industry@siemens.com](mailto:sibrain.industry@siemens.com)  
<http://www.siemens.com/sitrain>

### Dimensional drawings

**3RW44 2., 3RW44 3. and 3RW44 4. for High-Feature applications**

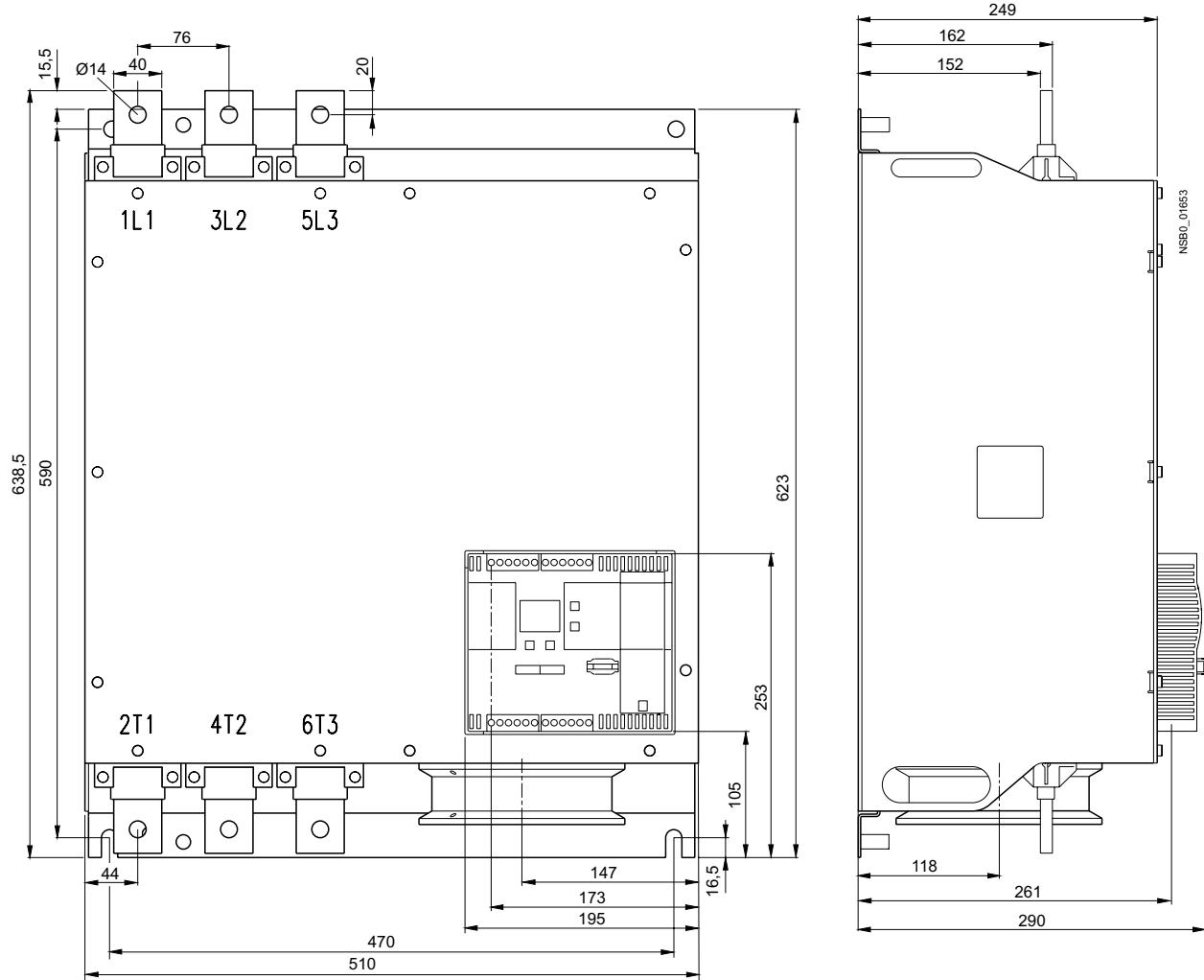


Type/Dimension (mm)	a	b	c	d	e	f	g	h	i	k	l	m	n	o	p	q
<b>3RW44 2.</b>	180	170	37	11	167	100	240	270	180	148	7,5	153	7	184	6,6	M6, 10 Nm
<b>3RW44 3.</b>	180	170	37	17	167	100	240	270	180	148	7,5	153	7	198	9	M6, 10 Nm
<b>3RW44 4.</b>	210	210	48	25	190	140	269	298	205	166	16	166	9	230	11	M8, 15 Nm

# 3RW Soft Starters

## Project planning aids

### 3RW44 5. for High-Feature applications



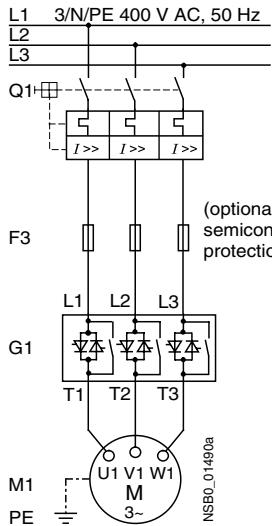
### Schematics

#### 3RW44 connection examples for main and control circuits

##### Main circuit

Possibility 1a:

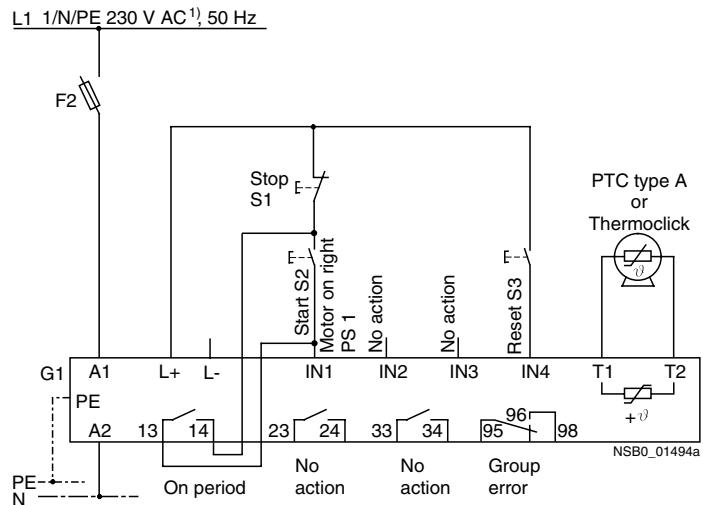
Inline circuit with circuit-breaker and SITOR fuse  
(semiconductor protection only)



##### Control circuit

Possibility 1:

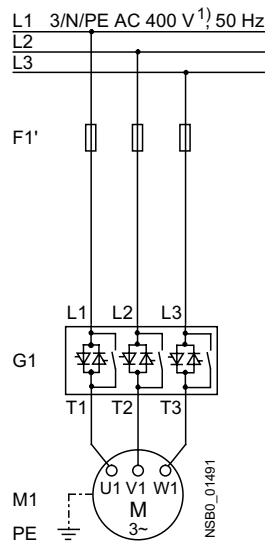
Control by pushbutton



##### Main circuit

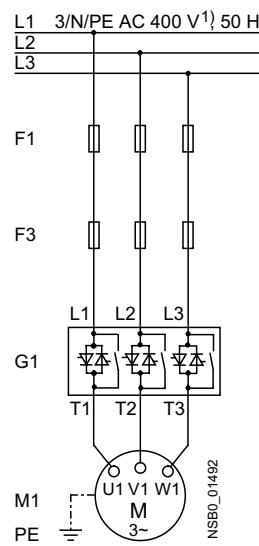
Possibility 1b:

Inline circuit with full-range protection (line and semiconductor protection)



##### Possibility 1c:

Inline circuit with line and SITOR fuse  
(semiconductor protection only)



1) Permissible values for main and control voltage,  
see Technical Specifications.

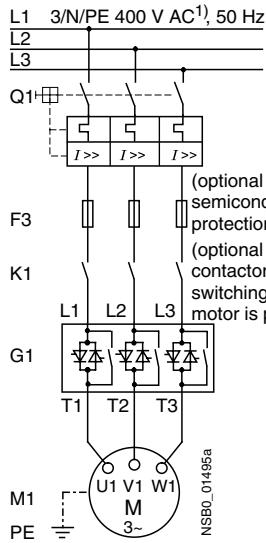
# 3RW Soft Starters

## Project planning aids

### Main circuit

Possibility 2:

Inline circuit with main contactor



1) Permissible values for main and control voltage,  
see Technical Specifications.

2) **Caution. Risk of restarting!**

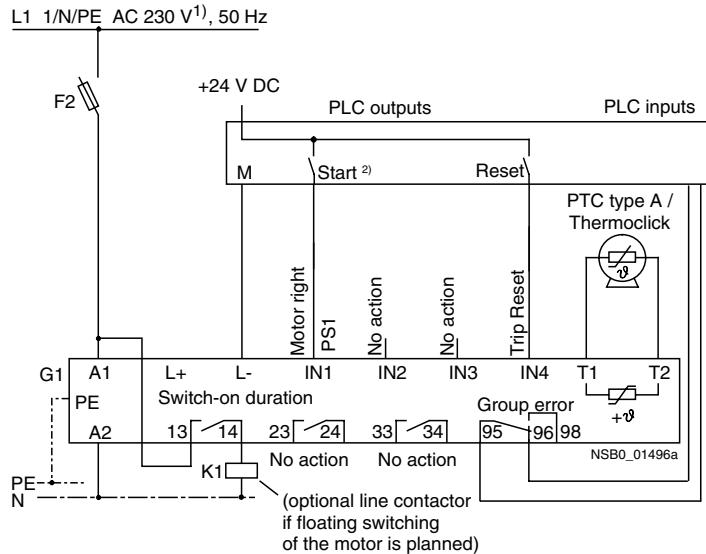
The start command (e.g. from the PLC) must be reset prior to a reset command because a new, automatic restart will take place automatically if a start command is active after the reset command. This applies especially in case of motor protection tripping.

For safety reasons we recommend incorporating the group error output (terminals 95 and 96) in the controller.

### Control circuit

Possibility 2:

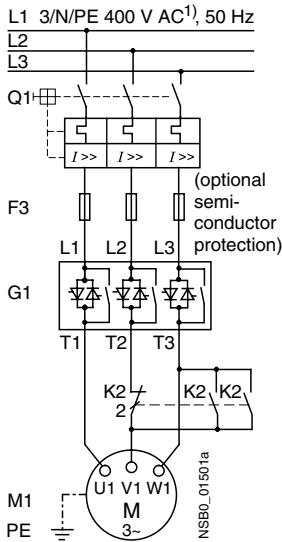
Control of a main contactor and control by means of PLC



## Project planning aids

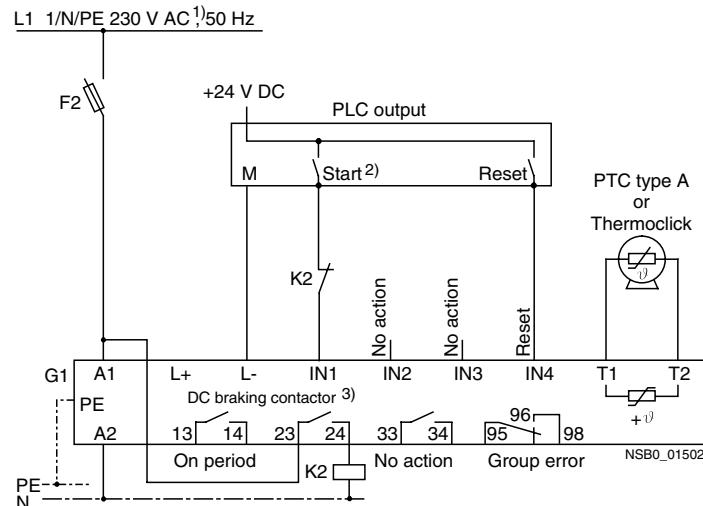
### Main circuit

Possibility 3a:  
Inline circuit with ramp-down function DC braking<sup>3)</sup>  
(for device types 3RW44 22 to 3RW44 25)



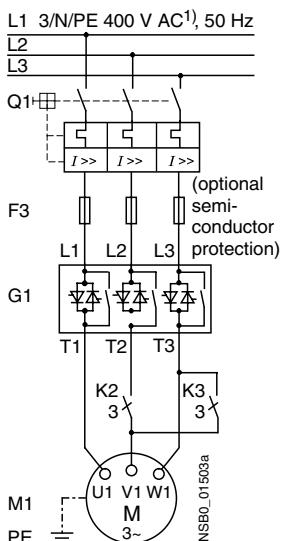
### Control circuit

Possibility 3a:  
Control of the braking contactor<sup>3)</sup>



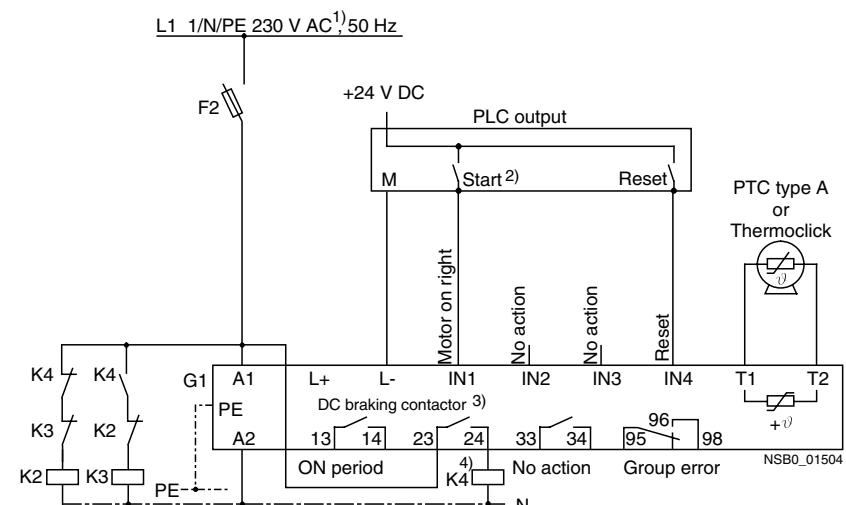
### Main circuit

Possibility 3b:  
Inline circuit with ramp-down function DC braking<sup>3)</sup>  
(for device types 3RW44 26 to 3RW44 47)



### Control circuit

Possibility 3b:  
Control of the braking contactor<sup>3)</sup>



1) Permissible values for main and control voltage, see Technical Specifications.

2) **Caution. Risk of restarting!**

The start command (e.g. from the PLC) must be reset prior to a reset command because a new, automatic restart will take place automatically if a start command is active after the reset command. This applies especially in case of motor protection tripping.  
For safety reasons we recommend incorporating the group error output (terminals 95 and 96) in the controller.

3) If the ramp-down function "Combined braking" is selected, no braking contactor is required.

If the ramp-down function "DC braking" is selected, a braking contactor must be used in addition. Type, see Fuse Coordination (inline circuit) on pages 6/21 to 6/23.  
For applications with large centrifugal masses ( $J_{Load} > J_{Motor}$ ) we recommend the function "DC braking".  
The output 2 must be switched over to "DC braking contactor".

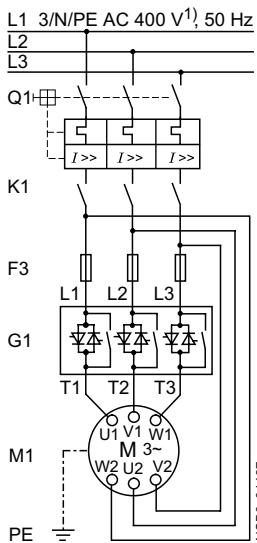
4) Auxiliary relay K4, e.g.:  
LZX:RT4A4T30 (230 V AC rated control supply voltage),  
LZX:RT4A4S15 (115 V AC rated control supply voltage).

# 3RW Soft Starters

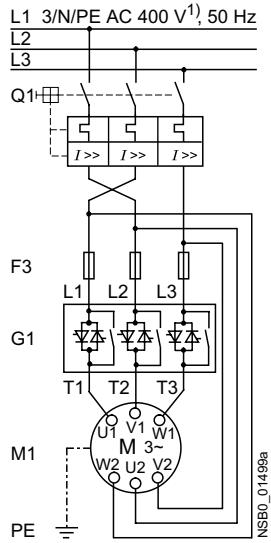
## Notes

### Main circuit

Possibility 4a:  
Inside-delta circuit

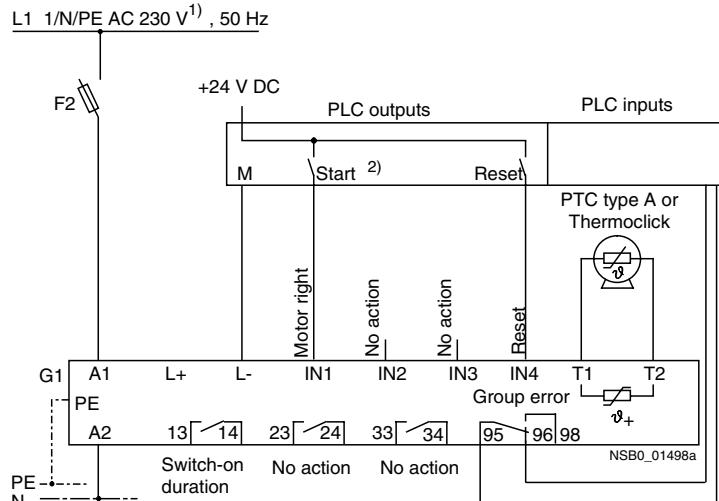


Possibility 4b:  
Change of direction of rotation for  
inside-delta circuit



### Control circuit

Possibility 4:  
Control by means of PLC



1) Permissible values for main and control voltage,  
see Technical Specifications.

2) **Caution. Risk of restarting!**

The start command (e.g. from the PLC) must be reset prior to a reset command because a new, automatic restart will take place automatically if a start command is active after the reset command. This applies especially in case of motor protection tripping.

For safety reasons we recommend incorporating the group error output (terminals 95 and 96) in the controller.

# Appendix

## Conditions of sale and delivery

### Terms and Conditions of Sale and Delivery

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Surcharges shall be charged based on the quantities of the materials which are contained in the relevant products.

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<http://www.siemens.com/automation/mall>

(Germany: A&D Mall Online-Help System)

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The deciding factors are the AL or ECCN export authorization indicated on order confirmations, delivery notes and invoices.

Errors excepted and subject to change without prior notice.

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