

Say Goodbye to Motor Failure !

บอกลาปัญหามอเตอร์ไหม้

เลือกใช้ EOCR

Digital Electronic Motor Protection Relay

EOCR - FDE

0.5 - 960 A

- หน้าจอโชว์กระแสแต่ละเฟส พร้อมบอกเปอร์เซ็นต์พิกัดโหลดของมอเตอร์
- แสดงสาเหตุการทรูป เจาะลิกถึงปัญหา โหลดค่าพร้อมบันทึก
- ส่งสัญญาณเตือนเมื่อกระแสมอเตอร์ผิดปกติ
- ปรับตั้งค่าด้วยระบบดิจิตอล
- มีฟังก์ชันป้องกันมอเตอร์หลากหลายครบถ้วน
- EOCR - FDE เพียงรุ่นเดียวสามารถใช้กับ Motor ได้ทุกขนาด (ตัดปัญหาการเก็บ Stock และขนาด)
- เป็นเครื่องมือตรวจเช็ค วางแผน ตรวจสอบบำรุงรักษามอเตอร์



EOCR-FDE



EOCR-3DE



NEW
EOCR - SSD

0.5~6 A
3.0~30 A
10~60 A

EOCR a company of
Schneider
Electric



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EOCR-SSD



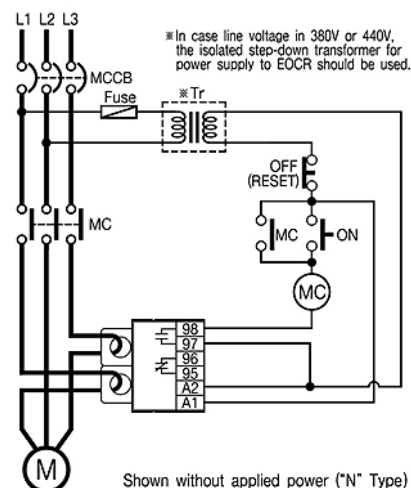
- Microprocessor Control Unit Based/2-CT Type
- Real Time Processing/Higher Precision
- Current Setting Range
05Type:0.5~6A/30Type:3~30A/60Type:10~60A
- Indicating real current on the display
- Trip cause digital display for easy trouble shooting
- Reset:Manual(instantaneous)/Electrical(remote)
- Load selection by

DIP switch: Single phase(1P)/Three phase(3P)

- Fail-safe(N)/Non-Fail-safe(R)

➤ Protection

- Over-current : Trip time 0 sec $I_s < I_n$
- Phase Loss : Trip time 3 sec
- Locked Rotor : Trip time 0.5sec after elapse of dt
>2times OC setting value



➤ Typical wiring

Over-Current Setting	Current	05	0.5 ~ 6A
		30	3.0 ~ 30A
		60	10 ~ 60A
	Starting delay time	D-TIME	1 ~ 30 sec
	Trip time	O-TIME	0.5, 1~10 sec
Operating t-c characteristic		Over-Current	Definite
Tolerance		Current	±5%
		TIME	±5%
Environment	Temperature	Operation	-20 ~ 60 °C
		Store	-30 ~ 80 °C
	Humidity		30~85% RH Non-condensing
Control Power		220 : 220VAC±15%, 50/60Hz	
		110 : 110VAC ±15%, 50/60Hz	
Output relay		2-SPST	3A / 250VAC Resistive
Insulation	Between casing and circuit		Over 10MΩ, 500VDC
Dielectric Strengths	Between casing and circuit		2000VAC 60Hz, 1min
	Between open contacts		1000VAC 60Hz, 1min
	between circuit		2000VAC 60Hz, 1min
Reset		Manual/Electrical	
Installation		35mm DIN-Rail or Panel Mounting	





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EOCR-3DE/FDE



- Compact Design
- MCU(Microprocessor Control Unit) Based
- Three Integral Current Transformers
- Multiple Protection Functions
- Digital Ammeter/3 Phase Current Display
- Troubleshooting/Trip Cause Memory, Display
- Adjustable Operating Features by Mode switch
- Wide Current Adjustment Range
- Selectable Time-Current Characteristics(Inverse/Definite)
- Manual(Instantaneous)/Electrical(Remote)Reset
- Test Function
- Ambient Insensitive
- Selectable Fail-safe and Non-fail-safe Operation Modes
- Inverter (20~400Hz)

➤ Protection

Protective Item	Trip Time
Over-current	DEF : 0.2~30sec INV : 1~30
Undercurrent	0.5~30 sec
Phase Loss	within 3 sec
Phase Unbalance	within 8 sec
Phase Reversal	0.1~0.3 sec
Locked Rotor	Lock : within 0.5sec after D-time(in DEF set)
	Stall : 0.05 ~ 10sec (in DEF set)

➤ Specification

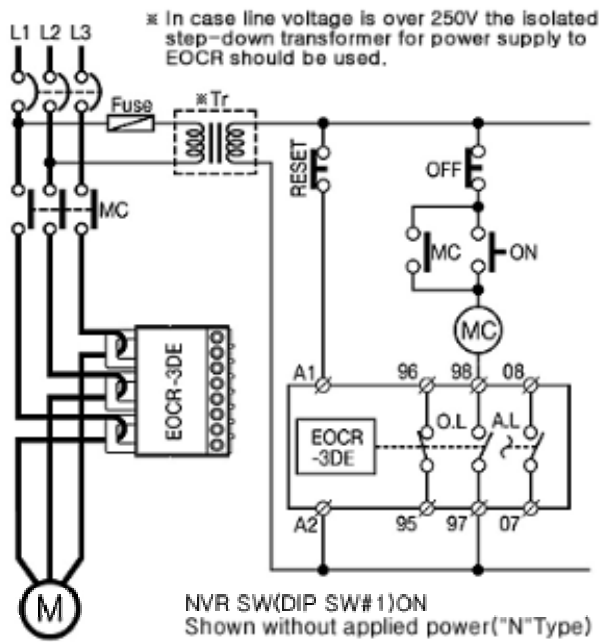
Current Range	Over Current	0.5~960A(Over 60A with External CTs)	
	Under Current	0.5~59A/OFF(Over 60A with External CTs)	
	Phase Unbalance	5~50%	
Alert Setting		50~100% of Oc setting	
Time Setting Range	Start Delay Time (D-TIME)	1~200sec (Definitive)	
	Trip Delay Time Setting (O-TIME)	INV	1-30
DEF		0.2-30 sec	
Control Voltage		110VAC±15%, 220VAC±15%, 24VAC/DC	
Output Relay	OC/UC	2-SPST, 3A/250VAC Resistive	
	AL/UC	1-SPST, 3A/250VAC Resistive	
Time Characteristic	In/"tc"mode	Inverse	
	dE/"tc"mode	Definite	
Troubleshooting/Trip Indication		LED Display(3 Trip causes memory)	
Current Sensing		3-CT	
Mounting		35mm DIN-Rail/Panel	



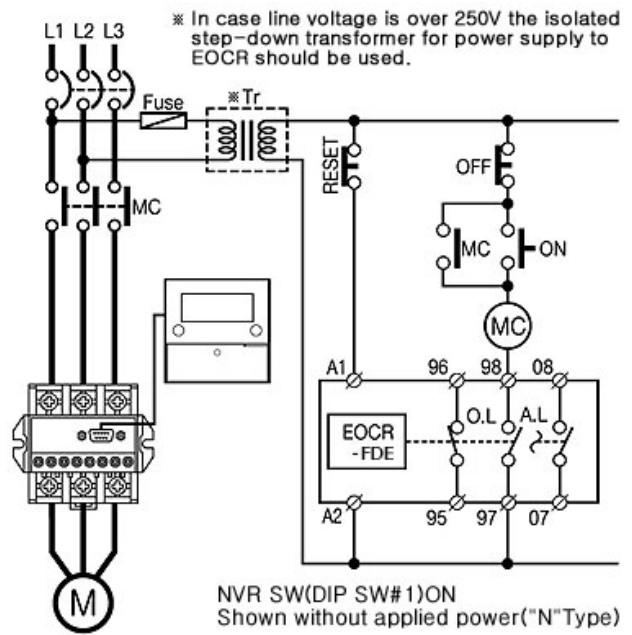
Say Goodbye to Motor Failure by Digital Electronic Motor Protection Relay EOCR

TiNAMICS... Solutions Provider in engineering systems with precision resources

THAILAND



EOCR-3DE



EOCR-FDE



Protective Item	Trip Time
Over-current	DEF : 0.2 ~ 30 sec, INV : 1~30
Undercurrent	0.5~30 sec
Phase Loss	within 3 sec
Phase Unbalance	8 sec
Phase Reversal	0.1~0.3 sec
Locked Rotor	Lock : within 0.5 sec after dt Stall : 0.05~10 sec(in DEF set)
Ground Fault	0.05~10 sec

Protective Item	Trip Time
Over-current	DEF:0.2~30 sec, INV:1~30 class
Under-current	0.5~30 sec
Phase Reversal	0.1~0.3 sec
Phase Unbalance	within 8 sec
Ground Fault	DEF:0.1~10 sec, INV:1~10 class
Locked Rotor	0.5 sec after d-time
Stall	0.05~10 sec

